Orientation Sensor Test

1

dTS (ms): 130111

ACC aX: 0.0000 aY: 0.0000 aZ: 0.0000

Gyro gX: 0.0000 gY: 0.0000 gZ: 0.0000

Angles X: nan Y: nan Z: nan

G force: 0.0000

1

dTS (ms): 10123

ACC aX: 0.0000 aY: 0.0000 aZ: 0.0000

Gyro gX: 0.0000 gY: 0.0000 gZ: 0.0000

Angles X: nan Y: nan Z: nan

G force: 0.0000

1

dTS (ms): 10121

ACC aX: -0.3700 aY: 4.8300 aZ: 7.6300

Gyro gX: 8.6875 gY: -5.6875 gZ: 3.5625

Angles X: -32.3349 Y: 2.3463 Z: -0.6803

G force: 4.9708

1

dTS (ms): 21112

ACC aX: -0.5600 aY: 5.4100 aZ: 8.2400

Gyro gX: -4.7500 gY: 1.4375 gZ: 2.8125

Angles X: -33.0091 Y: 2.9875 Z: -0.8854

G force: 7.6667

1

dTS (ms): 10220

ACC aX: -0.6500 aY: 5.4200 aZ: 8.1600

Gyro gX: 0.5000 gY: -2.0000 gZ: -12.1875

Angles X: -33.3651 Y: 3.4810 Z: -1.0435

G force: 8.8494

1

dTS (ms): 10222

ACC aX: -0.1200 aY: 5.1700 aZ: 8.5000

Gyro gX: 7.1250 gY: 9.8125 gZ: -7.1250

Angles X: -32.1744 Y: 1.8664 Z: -0.5383

G force: 9.4502

1

dTS (ms): 10220

ACC aX: 0.1200 aY: 5.7000 aZ: 8.4800

Gyro gX: -10.7500 gY: 6.6250 gZ: 11.9375

Angles X: -33.1613 Y: 0.4209 Z: -0.1253

G force: 9.8692

1

dTS (ms): 10221

ACC aX: 0.2800 aY: 5.4500 aZ: 8.3600

Gyro gX: -7.4375 gY: -0.1875 gZ: 5.9375

Angles X: -33.1279 Y: -0.7003 Z: 0.2083

G force: 9.9305

1

dTS (ms): 10213

ACC aX: -0.1700 aY: 5.1500 aZ: 8.1900

Gyro gX: 1.3125 gY: -2.0625 gZ: 0.5625

Angles X: -32.6031 Y: 0.2276 Z: -0.0666

G force: 9.7892

1

dTS (ms): 10220

ACC aX: 0.0600 aY: 5.2200 aZ: 8.3800

Gyro gX: -2.1875 gY: -1.0625 gZ: -2.0000

Angles X: -32.2255 Y: -0.0903 Z: 0.0261

G force: 9.8350

1

dTS (ms): 10221

ACC aX: 0.3200 aY: 5.4800 aZ: 8.5000

Gyro gX: -3.3125 gY: 1.5000 gZ: -2.3125

Angles X: -32.5511 Y: -1.0495 Z: 0.3064

G force: 9.9896

1

dTS (ms): 10220

ACC aX: 0.3600 aY: 5.4300 aZ: 8.4400

Gyro gX: -4.5000 gY: 5.1250 gZ: -5.8750

Angles X: -32.6639 Y: -1.6035 Z: 0.4699

G force: 10.0182

1

dTS (ms): 10221

ACC aX: 0.5800 aY: 5.6600 aZ: 8.1700

Gyro gX: -2.8750 gY: 2.6875 gZ: -4.0000

Angles X: -33.7873 Y: -2.5562 Z: 0.7764

G force: 9.9813

1

dTS (ms): 10220

ACC aX: 1.0700 aY: 5.6000 aZ: 8.1200

Gyro gX: -0.0625 gY: 7.9375 gZ: -8.0625

Angles X: -34.2279 Y: -4.5502 Z: 1.4017

G force: 9.9433

1

dTS (ms): 10220

ACC aX: 1.5000 aY: 5.8900 aZ: 8.3100

Gyro gX: -5.8750 gY: 5.5625 gZ: -2.1250

Angles X: -34.8406 Y: -6.6885 Z: 2.1008

G force: 10.1310

1

dTS (ms): 10221

ACC aX: 1.8500 aY: 5.8500 aZ: 7.9000

Gyro gX: -3.0000 gY: 11.5000 gZ: -9.3125

Angles X: -35.7547 Y: -8.8603 Z: 2.8630

G force: 10.0534

1

dTS (ms): 10222

ACC aX: 2.5100 aY: 5.7400 aZ: 7.8200

Gyro gX: -4.3750 gY: 5.8125 gZ: -9.8750

Angles X: -36.0401 Y: -11.9617 Z: 3.9039

G force: 10.0229

1

dTS (ms): 10222

ACC aX: 3.0800 aY: 5.7400 aZ: 7.3000

Gyro gX: -5.9375 gY: 10.8125 gZ: -13.8125

Angles X: -37.1871 Y: -15.4393 Z: 5.2220

G force: 9.8746

1

dTS (ms): 10222

ACC aX: 3.8800 aY: 5.6500 aZ: 7.2200

Gyro gX: -2.0625 gY: 7.1250 gZ: -12.3750

Angles X: -37.6509 Y: -19.5802 Z: 6.7333

G force: 9.8977

1

dTS (ms): 10222

ACC aX: 4.7200 aY: 5.5500 aZ: 6.8100

Gyro gX: -9.0000 gY: 11.8125 gZ: -12.5625

Angles X: -38.4689 Y: -24.3664 Z: 8.6159

G force: 9.9102

1

dTS (ms): 10223

ACC aX: 5.5100 aY: 5.2500 aZ: 6.4600

Gyro gX: -0.8750 gY: 9.7500 gZ: -18.1250

Angles X: -38.8036 Y: -29.4084 Z: 10.5609

G force: 9.9187

1

dTS (ms): 10223

ACC aX: 5.9700 aY: 5.0200 aZ: 6.3700

Gyro gX: -2.3750 gY: 13.8125 gZ: -18.1250

Angles X: -38.5028 Y: -33.2569 Z: 11.9091

G force: 9.9840

1

dTS (ms): 10230

ACC aX: 6.6000 aY: 4.8900 aZ: 5.6700

Gyro gX: -6.8750 gY: 10.3125 gZ: -10.1250

Angles X: -39.6913 Y: -37.7387 Z: 14.0645

G force: 9.9562

1

dTS (ms): 10230

ACC aX: 7.2600 aY: 4.2800 aZ: 5.1600

Gyro gX: -5.5625 gY: 6.6250 gZ: -9.9375

Angles X: -39.6826 Y: -42.9698 Z: 16.1670

G force: 9.8813

1

dTS (ms): 10222

ACC aX: 7.7900 aY: 3.6500 aZ: 4.4000

Gyro gX: -6.5625 gY: 10.1875 gZ: -13.1250

Angles X: -39.6800 Y: -48.8275 Z: 18.6021

G force: 9.7184

1

dTS (ms): 10230

ACC aX: 8.3100 aY: 3.5500 aZ: 3.8500

Gyro gX: -6.1250 gY: 17.3750 gZ: -17.4375

Angles X: -41.1795 Y: -53.7860 Z: 21.5747

G force: 9.7450

1

dTS (ms): 10230

ACC aX: 8.7400 aY: 3.0700 aZ: 3.4500

Gyro gX: -5.0000 gY: 13.7500 gZ: -12.8750

Angles X: -41.4196 Y: -58.4158 Z: 23.8689

G force: 9.7962

1

dTS (ms): 10230

ACC aX: 8.9800 aY: 2.4700 aZ: 2.5100

Gyro gX: -5.6875 gY: 15.5000 gZ: -12.3750

Angles X: -42.8430 Y: -63.9807 Z: 27.5393

G force: 9.6749

1

dTS (ms): 10230

ACC aX: 9.4200 aY: 2.0800 aZ: 1.8700

Gyro gX: -0.7500 gY: 12.8750 gZ: -12.6875

Angles X: -45.1628 Y: -69.2527 Z: 32.0458

G force: 9.7240

1

dTS (ms): 10230

ACC aX: 9.6800 aY: 1.7000 aZ: 1.4300

Gyro gX: 0.5625 gY: 10.5000 gZ: -8.6250

Angles X: -47.2640 Y: -73.6097 Z: 36.2560

G force: 9.8149

1

dTS (ms): 10222

ACC aX: 9.6700 aY: 1.1900 aZ: 0.7900

Gyro gX: 1.1250 gY: 8.5000 gZ: -10.2500

Angles X: -50.8024 Y: -78.0309 Z: 42.0881

G force: 9.7681

1

dTS (ms): 10222

ACC aX: 9.9700 aY: 0.8100 aZ: 0.4700

Gyro gX: -2.8750 gY: 6.6875 gZ: -2.8125

Angles X: -54.0757 Y: -81.7272 Z: 47.6447

G force: 9.8865

1

dTS (ms): 10222

ACC aX: 9.8000 aY: 0.7000 aZ: 0.3100

Gyro gX: 1.6875 gY: -1.0000 gZ: -0.5000

Angles X: -58.8477 Y: -83.8475 Z: 53.7233

G force: 9.8493

1

dTS (ms): 10221

ACC aX: 9.8500 aY: 0.9600 aZ: 0.4800

Gyro gX: -0.5000 gY: 0.0625 gZ: 1.7500

Angles X: -61.3897 Y: -83.8158 Z: 56.0961

G force: 9.8817

1

dTS (ms): 10221

ACC aX: 9.8500 aY: 0.7100 aZ: 0.5400

Gyro gX: 1.1875 gY: -0.8750 gZ: -0.1875

Angles X: -57.0154 Y: -84.3873 Z: 52.4285

G force: 9.8858

1

dTS (ms): 10222

ACC aX: 9.6700 aY: 0.6900 aZ: 0.2700

Gyro gX: 1.1250 gY: -0.6250 gZ: 0.0625

Angles X: -62.6317 Y: -85.0838 Z: 58.3495

G force: 9.7818

1

dTS (ms): 10221

ACC aX: 9.7100 aY: 0.7700 aZ: 0.3200

Gyro gX: -0.0625 gY: -0.8750 gZ: 0.3750

Angles X: -65.2662 Y: -85.0923 Z: 60.8868

G force: 9.7619

1

dTS (ms): 10222

ACC aX: 9.7700 aY: 0.5900 aZ: 0.3200

Gyro gX: -0.8750 gY: -0.1875 gZ: 1.0000

Angles X: -63.4127 Y: -85.6332 Z: 59.5728

G force: 9.7786

1

dTS (ms): 10222

ACC aX: 9.8300 aY: 0.9600 aZ: 0.4300

Gyro gX: -1.8750 gY: -6.8125 gZ: 11.0000

Angles X: -64.9699 Y: -84.6720 Z: 60.2348

G force: 9.8366

1

dTS (ms): 10223

ACC aX: 9.8200 aY: 1.1200 aZ: 0.8600

Gyro gX: 2.0000 gY: -6.8125 gZ: 6.0625

Angles X: -56.7961 Y: -83.1325 Z: 51.2303

G force: 9.8792

1

dTS (ms): 10221

ACC aX: 9.5900 aY: 1.4700 aZ: 1.3000

Gyro gX: 4.4375 gY: -11.5000 gZ: 10.6875

Angles X: -51.2435 Y: -80.5811 Z: 44.2516

G force: 9.8207

1

dTS (ms): 10223

ACC aX: 9.6100 aY: 1.9100 aZ: 1.7500

Gyro gX: 2.6875 gY: -8.8125 gZ: 9.2500

Angles X: -48.7623 Y: -77.4509 Z: 39.9454

G force: 9.8813

1

dTS (ms): 10220

ACC aX: 9.3400 aY: 2.1900 aZ: 2.2500

Gyro gX: 1.7500 gY: -7.8750 gZ: 10.0000

Angles X: -45.8530 Y: -74.1480 Z: 35.4459

G force: 9.8520

1

dTS (ms): 10222

ACC aX: 9.0800 aY: 2.6300 aZ: 2.4000

Gyro gX: 6.2500 gY: -10.3125 gZ: 8.6250

Angles X: -46.9436 Y: -71.1061 Z: 34.4822

G force: 9.7861

1

dTS (ms): 10221

ACC aX: 8.9500 aY: 3.1400 aZ: 3.0300

Gyro gX: 0.5625 gY: -7.3750 gZ: 8.2500

Angles X: -46.3651 Y: -67.1722 Z: 31.7486

G force: 9.8614

1

dTS (ms): 10221

ACC aX: 8.4500 aY: 3.1800 aZ: 3.5100

Gyro gX: 6.3750 gY: -11.9375 gZ: 10.4375

Angles X: -43.8428 Y: -63.6712 Z: 28.0578

G force: 9.7488

1

dTS (ms): 10223

ACC aX: 8.0300 aY: 4.0100 aZ: 4.0300

Gyro gX: 1.4375 gY: -8.0000 gZ: 10.8750

Angles X: -44.4682 Y: -58.7177 Z: 25.9004

G force: 9.7685

1

dTS (ms): 10222

ACC aX: 7.7800 aY: 4.2000 aZ: 4.3400

Gyro gX: 3.0000 gY: -9.1875 gZ: 10.0625

Angles X: -44.2268 Y: -55.1076 Z: 23.9397

G force: 9.7970

1

dTS (ms): 10222

ACC aX: 7.3600 aY: 4.2000 aZ: 4.6500

Gyro gX: -0.3125 gY: -7.8750 gZ: 12.4375

Angles X: -42.9924 Y: -52.0960 Z: 21.7917

G force: 9.7132

1

dTS (ms): 10223

ACC aX: 6.7400 aY: 4.8000 aZ: 4.9900

Gyro gX: 5.0625 gY: -7.6250 gZ: 8.8750

Angles X: -43.5177 Y: -47.7796 Z: 20.0513

G force: 9.6627

1

dTS (ms): 10221

ACC aX: 6.2500 aY: 5.1700 aZ: 5.7300

Gyro gX: 7.8750 gY: -11.8125 gZ: 12.8125

Angles X: -42.6537 Y: -42.8936 Z: 17.4394

G force: 9.7814

1

dTS (ms): 10223

ACC aX: 5.5900 aY: 5.5300 aZ: 6.1600

Gyro gX: 2.6250 gY: -6.1875 gZ: 12.6875

Angles X: -42.2214 Y: -37.9724 Z: 15.1332

G force: 9.8661

1

dTS (ms): 10222

ACC aX: 5.0500 aY: 5.4700 aZ: 6.3300

Gyro gX: 4.8750 gY: -11.4375 gZ: 9.6875

Angles X: -41.4320 Y: -34.2195 Z: 13.2805

G force: 9.7965

1

dTS (ms): 10222

ACC aX: 4.3800 aY: 5.4800 aZ: 6.7900

Gyro gX: 6.5625 gY: -11.4375 gZ: 10.0000

Angles X: -39.9964 Y: -30.0711 Z: 11.1668

G force: 9.7553

1

dTS (ms): 10223

ACC aX: 3.7100 aY: 5.3300 aZ: 7.1500

Gyro gX: 7.0625 gY: -8.8750 gZ: 10.6250

Angles X: -38.1403 Y: -25.9824 Z: 9.1199

G force: 9.6786

1

dTS (ms): 10221

ACC aX: 3.1700 aY: 5.3700 aZ: 7.4200

Gyro gX: 4.7500 gY: -5.1875 gZ: 16.1875

Angles X: -36.8763 Y: -22.1928 Z: 7.4822

G force: 9.6673

1

dTS (ms): 10220

ACC aX: 2.5700 aY: 5.6300 aZ: 7.8900

Gyro gX: 2.0625 gY: -6.5625 gZ: 10.0625

Angles X: -36.0982 Y: -18.0885 Z: 5.9386

G force: 9.8449

1

dTS (ms): 10221

ACC aX: 1.6000 aY: 5.5100 aZ: 8.1000

Gyro gX: 5.8125 gY: -19.4375 gZ: 27.0000

Angles X: -35.0470 Y: -13.2244 Z: 4.1924

G force: 9.8595

1

dTS (ms): 10222

ACC aX: 1.0000 aY: 5.5700 aZ: 8.3200

Gyro gX: -0.8125 gY: -3.7500 gZ: 3.5625

Angles X: -34.3488 Y: -9.0501 Z: 2.8023

G force: 9.9492

1

dTS (ms): 10220

ACC aX: 0.0200 aY: 5.3500 aZ: 7.8100

Gyro gX: 3.5000 gY: -15.3750 gZ: 0.0000

Angles X: -34.3829 Y: -4.2485 Z: 1.3150

G force: 9.6546

1

dTS (ms): 10220

ACC aX: 0.6400 aY: 5.8200 aZ: 8.3700

Gyro gX: -4.5625 gY: 7.4375 gZ: -3.7500

Angles X: -34.6252 Y: -3.8785 Z: 1.2094

G force: 9.9624

1

dTS (ms): 10220

ACC aX: 0.6200 aY: 5.7900 aZ: 7.9300

Gyro gX: 1.3125 gY: 1.5625 gZ: -0.0625

Angles X: -35.4508 Y: -3.7337 Z: 1.1938

G force: 9.8933

1

dTS (ms): 10213

ACC aX: 0.6400 aY: 5.5800 aZ: 8.1000

Gyro gX: -0.9375 gY: 0.1875 gZ: 0.6250

Angles X: -34.9631 Y: -3.7278 Z: 1.1744

G force: 9.8729

1

dTS (ms): 10213

ACC aX: 0.5900 aY: 5.7100 aZ: 8.0400

Gyro gX: -1.5625 gY: -0.4375 gZ: 0.8125

Angles X: -35.1938 Y: -3.5606 Z: 1.1296

G force: 9.8761

1

dTS (ms): 10220

ACC aX: 0.5700 aY: 5.7700 aZ: 7.9700

Gyro gX: -1.0625 gY: -0.1250 gZ: 1.1875

Angles X: -35.5837 Y: -3.4260 Z: 1.0997

G force: 9.8648

1

dTS (ms): 10213

ACC aX: 0.5800 aY: 5.7400 aZ: 8.0800

Gyro gX: 1.0625 gY: -1.5000 gZ: 2.9375

Angles X: -35.4767 Y: -3.3836 Z: 1.0826

G force: 9.8997

1

dTS (ms): 10213

ACC aX: 0.4700 aY: 5.7600 aZ: 8.0800

Gyro gX: 1.5000 gY: -1.0625 gZ: 2.3125

Angles X: -35.4807 Y: -3.0135 Z: 0.9643

G force: 9.9184

1

dTS (ms): 10212

ACC aX: 0.2600 aY: 5.6400 aZ: 8.0500

Gyro gX: -0.3125 gY: 0.6875 gZ: 6.0625

Angles X: -35.2259 Y: -2.1927 Z: 0.6962

G force: 9.8703

1

dTS (ms): 10213

ACC aX: 0.0900 aY: 5.8600 aZ: 8.1100

Gyro gX: 1.3125 gY: -2.2500 gZ: 6.6875

Angles X: -35.5717 Y: -1.2645 Z: 0.4057

G force: 9.9437

1

dTS (ms): 10213

ACC aX: 0.1200 aY: 5.8200 aZ: 7.8100

Gyro gX: 3.3750 gY: -3.9375 gZ: 2.5625

Angles X: -36.1830 Y: -0.9602 Z: 0.3137

G force: 9.8315

1

dTS (ms): 10213

ACC aX: -0.3600 aY: 5.6300 aZ: 8.0800

Gyro gX: 2.8750 gY: -4.6250 gZ: 4.6875

Angles X: -35.4592 Y: 0.7212 Z: -0.2306

G force: 9.8401

1

dTS (ms): 10220

ACC aX: -0.8100 aY: 5.5500 aZ: 8.1700

Gyro gX: 3.5625 gY: -4.1875 gZ: 6.5625

Angles X: -34.7593 Y: 2.9104 Z: -0.9111

G force: 9.8721

1

dTS (ms): 10220

ACC aX: -0.9400 aY: 5.4000 aZ: 8.1100

Gyro gX: 7.3750 gY: 0.7500 gZ: 4.9375

Angles X: -34.1565 Y: 4.3353 Z: -1.3325

G force: 9.8232

1

dTS (ms): 10212

ACC aX: -1.3800 aY: 4.7600 aZ: 8.1100

Gyro gX: 1.1250 gY: -7.3750 gZ: 14.0000

Angles X: -32.1337 Y: 6.5133 Z: -1.8777

G force: 9.6369

1

dTS (ms): 10221

ACC aX: -2.0500 aY: 4.5800 aZ: 8.7500

Gyro gX: 7.3125 gY: -5.3750 gZ: 10.2500

Angles X: -29.6214 Y: 9.4465 Z: -2.5030

G force: 9.8669

1

dTS (ms): 10221

ACC aX: -2.4600 aY: 4.3100 aZ: 8.5800

Gyro gX: 0.6875 gY: -12.2500 gZ: 7.3750

Angles X: -28.0090 Y: 12.1642 Z: -3.0446

G force: 9.8795

1

dTS (ms): 10222

ACC aX: -3.4000 aY: 4.1200 aZ: 8.1300

Gyro gX: 3.0000 gY: -14.2500 gZ: 14.6875

Angles X: -27.4012 Y: 16.6951 Z: -4.0973

G force: 9.7702

1

dTS (ms): 10223

ACC aX: -3.9800 aY: 3.8300 aZ: 8.1600

Gyro gX: 7.1250 gY: -7.0000 gZ: 9.5000

Angles X: -26.1805 Y: 20.6345 Z: -4.8477

G force: 9.7957

1

dTS (ms): 10221

ACC aX: -4.6200 aY: 3.8400 aZ: 8.7900

Gyro gX: 15.4375 gY: -9.8750 gZ: 16.0625

Angles X: -24.7315 Y: 23.5399 Z: -5.2311

G force: 10.2517

1

dTS (ms): 10230

ACC aX: -5.1200 aY: 2.4400 aZ: 7.8900

Gyro gX: 5.3125 gY: -14.6875 gZ: 11.2500

Angles X: -20.8231 Y: 28.0236 Z: -5.2506

G force: 9.9152

1

dTS (ms): 10223

ACC aX: -5.5900 aY: 1.7600 aZ: 7.6700

Gyro gX: 4.5625 gY: -11.8750 gZ: 10.8125

Angles X: -16.6870 Y: 32.0867 Z: -4.8300

G force: 9.7342

1

dTS (ms): 10223

ACC aX: -6.2300 aY: 1.3500 aZ: 7.2100

Gyro gX: 5.8125 gY: -11.5625 gZ: 11.6250

Angles X: -13.5192 Y: 36.6430 Z: -4.4952

G force: 9.6399

1

dTS (ms): 10223

ACC aX: -6.5300 aY: 0.5900 aZ: 7.2800

Gyro gX: 5.2500 gY: -6.1250 gZ: 5.0000

Angles X: -8.7577 Y: 39.5834 Z: -3.1569

G force: 9.6995

1

dTS (ms): 10220

ACC aX: -6.7100 aY: 0.1300 aZ: 7.0700

Gyro gX: 10.3125 gY: -12.0625 gZ: 7.0625

Angles X: -4.6262 Y: 41.8058 Z: -1.7677

G force: 9.7085

1

dTS (ms): 10221

ACC aX: -7.1600 aY: -0.1800 aZ: 6.5200

Gyro gX: 6.3750 gY: -10.3750 gZ: 7.6875

Angles X: -1.3722 Y: 45.0686 Z: -0.5694

G force: 9.6762

1

dTS (ms): 10222

ACC aX: -7.4700 aY: -0.6500 aZ: 6.2600

Gyro gX: 9.1250 gY: -0.1250 gZ: 13.1875

Angles X: 2.4939 Y: 47.7867 Z: 1.1049

G force: 9.7092

1

dTS (ms): 10220

ACC aX: -7.6600 aY: -1.3900 aZ: 6.0100

Gyro gX: 3.1875 gY: -15.3125 gZ: 8.1875

Angles X: 8.1395 Y: 49.7690 Z: 3.7806

G force: 9.7571

1

dTS (ms): 10220

ACC aX: -8.0300 aY: -1.8200 aZ: 5.0200

Gyro gX: 2.5625 gY: -13.6250 gZ: 8.8125

Angles X: 14.1374 Y: 53.5299 Z: 7.1575

G force: 9.6604

1

dTS (ms): 10221

ACC aX: -8.1400 aY: -2.3100 aZ: 4.6500

Gyro gX: -1.6875 gY: -9.3125 gZ: 7.8125

Angles X: 20.5850 Y: 55.8482 Z: 10.9953

G force: 9.6342

1

dTS (ms): 10222

ACC aX: -8.2900 aY: -2.4900 aZ: 4.2900

Gyro gX: 1.0625 gY: -7.5625 gZ: 2.6875

Angles X: 25.6312 Y: 57.7320 Z: 14.2951

G force: 9.6354

1

dTS (ms): 10221

ACC aX: -8.4000 aY: -2.8300 aZ: 4.0800

Gyro gX: -1.4375 gY: -10.0625 gZ: 6.6875

Angles X: 30.5653 Y: 58.7411 Z: 17.4849

G force: 9.6935

1

dTS (ms): 10223

ACC aX: -8.4600 aY: -2.7700 aZ: 3.7600

Gyro gX: 3.6875 gY: -8.3750 gZ: -1.8125

Angles X: 33.6559 Y: 60.0685 Z: 19.8370

G force: 9.6718

1

dTS (ms): 10222

ACC aX: -8.6400 aY: -2.8500 aZ: 3.2600

Gyro gX: 3.5625 gY: -10.5000 gZ: 0.9375

Angles X: 37.5817 Y: 61.9408 Z: 23.0827

G force: 9.6591

1

dTS (ms): 10222

ACC aX: -8.8500 aY: -2.7700 aZ: 2.6600

Gyro gX: 3.5000 gY: -6.1250 gZ: -2.8125

Angles X: 41.9411 Y: 64.5326 Z: 27.2060

G force: 9.6399

1

dTS (ms): 10221

ACC aX: -8.8700 aY: -2.8300 aZ: 2.6800

Gyro gX: 1.6875 gY: -2.3125 gZ: -1.3125

Angles X: 44.4106 Y: 65.5126 Z: 29.4302

G force: 9.6642

1

dTS (ms): 10221

ACC aX: -8.9400 aY: -2.5600 aZ: 2.1400

Gyro gX: 0.3750 gY: -2.7500 gZ: -3.4375

Angles X: 47.2841 Y: 67.7362 Z: 32.7467

G force: 9.5896

1

dTS (ms): 10222

ACC aX: -8.9800 aY: -2.6600 aZ: 2.4900

Gyro gX: 0.3750 gY: 1.2500 gZ: -0.8125

Angles X: 47.0674 Y: 67.8354 Z: 32.6450

G force: 9.6454

1

dTS (ms): 10221

ACC aX: -8.9800 aY: -2.6700 aZ: 2.4200

Gyro gX: -0.3125 gY: -1.3125 gZ: -0.7500

Angles X: 47.4751 Y: 68.0010 Z: 33.0429

G force: 9.6622

1

dTS (ms): 10223

ACC aX: -9.1000 aY: -2.5900 aZ: 2.3400

Gyro gX: 1.6875 gY: -0.0625 gZ: -0.6250

Angles X: 47.7066 Y: 68.5607 Z: 33.5458

G force: 9.7082

1

dTS (ms): 10222

ACC aX: -8.9700 aY: -2.6300 aZ: 2.3900

Gyro gX: 1.3125 gY: 0.7500 gZ: -1.2500

Angles X: 47.7234 Y: 68.4658 Z: 33.5020

G force: 9.6752

1

dTS (ms): 10221

ACC aX: -9.0500 aY: -2.4900 aZ: 2.3600

Gyro gX: -0.2500 gY: -1.3750 gZ: -1.3750

Angles X: 47.0802 Y: 68.8922 Z: 33.2731

G force: 9.6767

1

dTS (ms): 10223

ACC aX: -9.1200 aY: -2.4000 aZ: 2.2200

Gyro gX: -0.5625 gY: -0.6250 gZ: -1.3125

Angles X: 47.1608 Y: 69.6550 Z: 33.7844

G force: 9.6824

1

dTS (ms): 10223

ACC aX: -9.1300 aY: -2.4500 aZ: 2.1300

Gyro gX: -1.3125 gY: -2.4375 gZ: 1.4375

Angles X: 48.1541 Y: 70.0814 Z: 34.7972

G force: 9.6862

1

dTS (ms): 10222

ACC aX: -9.0900 aY: -2.5800 aZ: 2.1700

Gyro gX: 1.9375 gY: -0.1875 gZ: 0.6250

Angles X: 49.1421 Y: 69.8470 Z: 35.4107

G force: 9.6909

1

dTS (ms): 10221

ACC aX: -8.9900 aY: -2.5700 aZ: 2.2000

Gyro gX: 1.0000 gY: -0.1250 gZ: 1.3125

Angles X: 49.3044 Y: 69.5902 Z: 35.3762

G force: 9.6438

1

dTS (ms): 10221

ACC aX: -9.0900 aY: -2.4500 aZ: 2.0700

Gyro gX: -1.2500 gY: 0.7500 gZ: -0.1875

Angles X: 49.5742 Y: 70.1262 Z: 35.9159

G force: 9.6410

1

dTS (ms): 10221

ACC aX: -9.1000 aY: -2.5200 aZ: 2.2200

Gyro gX: 1.3125 gY: 1.2500 gZ: -1.3125

Angles X: 49.0445 Y: 69.9156 Z: 35.3782

G force: 9.6733

1

dTS (ms): 10221

ACC aX: -9.0300 aY: -2.5300 aZ: 2.1900

Gyro gX: -0.6875 gY: -4.6875 gZ: 1.5625

Angles X: 49.0862 Y: 69.7792 Z: 35.3261

G force: 9.6495

1

dTS (ms): 10222

ACC aX: -9.0400 aY: -2.3900 aZ: 2.2600

Gyro gX: 2.3125 gY: 1.0625 gZ: -0.2500

Angles X: 47.7281 Y: 69.9077 Z: 34.3667

G force: 9.6329

1

dTS (ms): 10221

ACC aX: -9.0400 aY: -2.3400 aZ: 1.9800

Gyro gX: -1.8125 gY: 0.3750 gZ: -3.1875

Angles X: 48.8089 Y: 70.6563 Z: 35.6537

G force: 9.5840

1

dTS (ms): 10222

ACC aX: -9.0900 aY: -2.4100 aZ: 2.2100

Gyro gX: 0.9375 gY: 7.0625 gZ: 0.5000

Angles X: 48.0676 Y: 70.4140 Z: 34.9328

G force: 9.6258

1

dTS (ms): 10220

ACC aX: -9.0900 aY: -2.2300 aZ: 2.5100

Gyro gX: -0.6250 gY: 6.0000 gZ: -5.4375

Angles X: 44.4574 Y: 70.0640 Z: 31.9739

G force: 9.6593

1

dTS (ms): 10222

ACC aX: -8.9800 aY: -1.9600 aZ: 2.8400

Gyro gX: -1.0625 gY: 8.8125 gZ: -6.1875

Angles X: 38.9272 Y: 69.5373 Z: 27.5689

G force: 9.6331

1

dTS (ms): 10222

ACC aX: -9.0300 aY: -1.7700 aZ: 3.2700

Gyro gX: -4.0000 gY: 6.6250 gZ: -5.5625

Angles X: 32.8935 Y: 68.5563 Z: 22.7530

G force: 9.6993

1

dTS (ms): 10222

ACC aX: -8.8100 aY: -1.5200 aZ: 3.6000

Gyro gX: 0.9375 gY: 12.7500 gZ: -5.5000

Angles X: 27.1508 Y: 67.2745 Z: 18.2542

G force: 9.6578

1

dTS (ms): 10222

ACC aX: -8.7800 aY: -1.0600 aZ: 4.1200

Gyro gX: -4.6250 gY: 6.5000 gZ: -7.6250

Angles X: 19.7392 Y: 65.6767 Z: 12.8136

G force: 9.6985

1

dTS (ms): 10222

ACC aX: -8.5400 aY: -0.5800 aZ: 4.5300

Gyro gX: -3.0625 gY: 11.2500 gZ: -5.0000

Angles X: 12.4826 Y: 63.7115 Z: 7.7752

G force: 9.6745

1

dTS (ms): 10222

ACC aX: -8.2700 aY: -0.4600 aZ: 5.1300

Gyro gX: -4.1250 gY: 10.0000 gZ: -8.5000

Angles X: 8.1032 Y: 60.6557 Z: 4.7456

G force: 9.6958

1

dTS (ms): 10220

ACC aX: -8.0700 aY: -0.0300 aZ: 5.4900

Gyro gX: -2.7500 gY: 9.3750 gZ: -9.2500

Angles X: 3.5415 Y: 58.0195 Z: 1.9643

G force: 9.7165

1

dTS (ms): 10220

ACC aX: -7.7600 aY: 0.2800 aZ: 6.0000

Gyro gX: -0.8125 gY: 12.6250 gZ: -7.4375

Angles X: -0.1118 Y: 54.8752 Z: -0.0580

G force: 9.7528

1

dTS (ms): 10222

ACC aX: -7.4500 aY: 0.8400 aZ: 6.1900

Gyro gX: 2.3750 gY: 13.2500 gZ: -8.0625

Angles X: -4.5025 Y: 52.2687 Z: -2.2099

G force: 9.7195

1

dTS (ms): 10221

ACC aX: -6.9800 aY: 0.9400 aZ: 6.6300

Gyro gX: 4.6250 gY: 17.3750 gZ: -8.6875

Angles X: -6.5684 Y: 48.9449 Z: -2.9922

G force: 9.6783

1

dTS (ms): 10221

ACC aX: -6.6000 aY: 1.4500 aZ: 7.3100

Gyro gX: -7.9375 gY: 7.7500 gZ: -10.1250

Angles X: -9.3080 Y: 44.8366 Z: -3.8470

G force: 9.8061

1

dTS (ms): 10222

ACC aX: -5.8300 aY: 2.0500 aZ: 7.8200

Gyro gX: 0.6875 gY: 14.8125 gZ: -10.5000

Angles X: -12.4669 Y: 39.8578 Z: -4.5356

G force: 9.8581

1

dTS (ms): 10223

ACC aX: -5.6100 aY: 2.4100 aZ: 8.0000

Gyro gX: -3.1875 gY: 8.5000 gZ: -8.8750

Angles X: -14.9357 Y: 36.5576 Z: -4.9584

G force: 9.9534

1

dTS (ms): 10222

ACC aX: -5.2200 aY: 2.5800 aZ: 8.0000

Gyro gX: -0.1250 gY: 9.5625 gZ: -7.4375

Angles X: -16.5884 Y: 33.9786 Z: -5.1005

G force: 9.9106

1

dTS (ms): 10222

ACC aX: -4.7800 aY: 2.8200 aZ: 8.1400

Gyro gX: 1.8750 gY: 6.3750 gZ: -4.9375

Angles X: -18.0035 Y: 31.2670 Z: -5.0766

G force: 9.8675

1

dTS (ms): 10221

ACC aX: -4.3300 aY: 2.9600 aZ: 8.3500

Gyro gX: -0.6250 gY: 7.9375 gZ: -4.6250

Angles X: -18.8554 Y: 28.3991 Z: -4.8117

G force: 9.8529

1

dTS (ms): 10221

ACC aX: -3.7100 aY: 2.8800 aZ: 8.6600

Gyro gX: -1.0625 gY: 11.3125 gZ: -5.0000

Angles X: -18.5964 Y: 24.9471 Z: -4.1484

G force: 9.8375

1

dTS (ms): 10223

ACC aX: -3.2700 aY: 3.0400 aZ: 8.7600

Gyro gX: -3.1250 gY: 11.0000 gZ: -7.0000

Angles X: -18.8997 Y: 21.9109 Z: -3.6908

G force: 9.8232

1

dTS (ms): 10223

ACC aX: -2.6000 aY: 3.3900 aZ: 8.7100

Gyro gX: -0.3125 gY: 9.0000 gZ: -6.5000

Angles X: -20.2162 Y: 18.4330 Z: -3.3138

G force: 9.7394

1

dTS (ms): 10222

ACC aX: -2.0100 aY: 3.6400 aZ: 9.1300

Gyro gX: -0.6250 gY: 10.3750 gZ: -7.1250

Angles X: -21.0755 Y: 14.6019 Z: -2.7305

G force: 9.8821

1

dTS (ms): 10223

ACC aX: -1.3300 aY: 3.9100 aZ: 8.9500

Gyro gX: -10.8125 gY: 15.7500 gZ: -8.6250

Angles X: -22.4767 Y: 10.8423 Z: -2.1606

G force: 9.8486

1

dTS (ms): 10230

ACC aX: -1.0300 aY: 3.9700 aZ: 8.8900

Gyro gX: 0.8125 gY: 11.5625 gZ: -6.5625

Angles X: -23.3523 Y: 8.2081 Z: -1.6990

G force: 9.8072

1

dTS (ms): 10221

ACC aX: -0.3000 aY: 4.1500 aZ: 9.0200

Gyro gX: -10.3125 gY: 4.9375 gZ: -7.6875

Angles X: -24.1048 Y: 4.6250 Z: -0.9880

G force: 9.8603

1

dTS (ms): 10222

ACC aX: -0.1000 aY: 4.3100 aZ: 8.5200

Gyro gX: 0.8125 gY: 8.9375 gZ: -4.9375

Angles X: -25.5860 Y: 2.4439 Z: -0.5550

G force: 9.6802

1

dTS (ms): 10220

ACC aX: 0.4500 aY: 4.4000 aZ: 8.7400

Gyro gX: 0.8125 gY: 6.5000 gZ: -4.2500

Angles X: -26.2142 Y: -0.3635 Z: 0.0846

G force: 9.7337

1

dTS (ms): 10212

ACC aX: 0.9600 aY: 4.7800 aZ: 8.7600

Gyro gX: 0.1875 gY: -6.5625 gZ: 1.2500

Angles X: -27.5520 Y: -3.2241 Z: 0.7907

G force: 9.8822

1

dTS (ms): 10213

ACC aX: 0.7100 aY: 4.5800 aZ: 8.5100

Gyro gX: -3.5000 gY: -0.8125 gZ: -1.8750

Angles X: -27.9534 Y: -3.7572 Z: 0.9355

G force: 9.7760

1

dTS (ms): 10220

ACC aX: 0.6700 aY: 4.6400 aZ: 8.5500

Gyro gX: -0.5000 gY: -0.5625 gZ: 1.1875

Angles X: -28.2472 Y: -3.8576 Z: 0.9710

G force: 9.7621

1

dTS (ms): 10220

ACC aX: 0.6500 aY: 4.8100 aZ: 8.5400

Gyro gX: -0.3125 gY: -1.5000 gZ: 0.1250

Angles X: -28.8773 Y: -3.8228 Z: 0.9846

G force: 9.7951

1

dTS (ms): 10220

ACC aX: 0.6400 aY: 4.8500 aZ: 8.4400

Gyro gX: -0.4375 gY: -4.3125 gZ: 1.2500

Angles X: -29.4298 Y: -3.7894 Z: 0.9955

G force: 9.7728

1

dTS (ms): 10220

ACC aX: 0.6400 aY: 4.8100 aZ: 8.5900

Gyro gX: -3.7500 gY: 1.4375 gZ: -0.2500

Angles X: -29.3287 Y: -3.7507 Z: 0.9818

G force: 9.8239

1

dTS (ms): 10220

ACC aX: 0.5400 aY: 4.9600 aZ: 8.3300

Gyro gX: -2.8125 gY: -3.8750 gZ: 5.5000

Angles X: -30.1181 Y: -3.4432 Z: 0.9267

G force: 9.7603

1

dTS (ms): 10220

ACC aX: 0.9700 aY: 4.6100 aZ: 8.5800

Gyro gX: 2.5000 gY: 9.7500 gZ: 0.6875

Angles X: -29.0902 Y: -4.6796 Z: 1.2148

G force: 9.7725

1

dTS (ms): 10212

ACC aX: 0.4000 aY: 4.1400 aZ: 8.8800

Gyro gX: -5.2500 gY: -20.3750 gZ: -5.5625

Angles X: -26.8321 Y: -3.3918 Z: 0.8093

G force: 9.7827

1

dTS (ms): 10222

ACC aX: 1.6600 aY: 4.8100 aZ: 9.4600

Gyro gX: 7.1250 gY: 18.4375 gZ: -2.3125

Angles X: -26.9002 Y: -6.5427 Z: 1.5663

G force: 10.2985

1

dTS (ms): 10221

ACC aX: 0.8100 aY: 4.8400 aZ: 7.5200

Gyro gX: 2.5625 gY: -3.8750 gZ: -1.4375

Angles X: -29.9300 Y: -5.8449 Z: 1.5636

G force: 9.5600

1

dTS (ms): 10213

ACC aX: 1.5300 aY: 3.9000 aZ: 9.3500

Gyro gX: -20.3125 gY: -9.5000 gZ: -4.3125

Angles X: -25.8072 Y: -7.4152 Z: 1.7010

G force: 9.9149

1

dTS (ms): 10222

ACC aX: 1.6500 aY: 4.6000 aZ: 8.6700

Gyro gX: 41.0625 gY: 30.8125 gZ: 2.8125

Angles X: -26.9842 Y: -8.5890 Z: 2.0644

G force: 9.9322

1

dTS (ms): 10220

ACC aX: 2.0700 aY: 3.5800 aZ: 9.7200

Gyro gX: -22.8125 gY: -23.6250 gZ: -1.0625

Angles X: -23.1741 Y: -10.1389 Z: 2.0840

G force: 10.2593

1

dTS (ms): 10231

ACC aX: 1.4200 aY: 5.1300 aZ: 8.2500

Gyro gX: -15.1250 gY: -4.1250 gZ: 5.8125

Angles X: -27.8761 Y: -9.1819 Z: 2.2834

G force: 9.9875

1

dTS (ms): 10221

ACC aX: 0.8800 aY: 4.5500 aZ: 8.3700

Gyro gX: 10.2500 gY: -17.8750 gZ: 8.8750

Angles X: -28.2296 Y: -7.0762 Z: 1.7815

G force: 9.7506

1

dTS (ms): 10221

ACC aX: 0.8700 aY: 4.7200 aZ: 8.9800

Gyro gX: -9.0625 gY: 0.3750 gZ: 5.8125

Angles X: -27.9473 Y: -5.8569 Z: 1.4586

G force: 9.9861

1

dTS (ms): 10213

ACC aX: 0.2400 aY: 4.2900 aZ: 9.0400

Gyro gX: -4.0625 gY: -7.8750 gZ: 5.5000

Angles X: -26.5345 Y: -3.3895 Z: 0.7994

G force: 9.9887

1

dTS (ms): 10213

ACC aX: 0.6200 aY: 5.0700 aZ: 8.7600

Gyro gX: -4.9375 gY: 3.1875 gZ: -7.5000

Angles X: -28.4871 Y: -3.4552 Z: 0.8774

G force: 10.0674

1

dTS (ms): 10221

ACC aX: 0.8500 aY: 5.0800 aZ: 8.5100

Gyro gX: 0.0000 gY: -5.3750 gZ: 2.3750

Angles X: -29.7703 Y: -4.2475 Z: 1.1295

G force: 9.9985

1

dTS (ms): 10213

ACC aX: 0.4200 aY: 4.7900 aZ: 8.6200

Gyro gX: 3.3750 gY: -5.2500 gZ: -2.3125

Angles X: -29.3817 Y: -3.2585 Z: 0.8545

G force: 9.9266

1

dTS (ms): 10213

ACC aX: 0.5200 aY: 4.8900 aZ: 8.6100

Gyro gX: -3.7500 gY: -3.2500 gZ: -6.3750

Angles X: -29.4985 Y: -3.1198 Z: 0.8215

G force: 9.9204

1

dTS (ms): 10221

ACC aX: 0.3200 aY: 4.9900 aZ: 8.5400

Gyro gX: -4.1250 gY: -1.2500 gZ: -4.1875

Angles X: -29.9380 Y: -2.4239 Z: 0.6482

G force: 9.9062

1

dTS (ms): 10221

ACC aX: 0.6500 aY: 4.9400 aZ: 8.7500

Gyro gX: 1.6250 gY: -1.0000 gZ: 1.1250

Angles X: -29.6666 Y: -3.1316 Z: 0.8295

G force: 9.9952

1

dTS (ms): 10213

ACC aX: 0.5400 aY: 5.0200 aZ: 8.4900

Gyro gX: -3.1250 gY: -0.8125 gZ: -1.2500

Angles X: -30.1746 Y: -3.1329 Z: 0.8448

G force: 9.9303

1

dTS (ms): 10221

ACC aX: 0.6300 aY: 5.3800 aZ: 8.1700

Gyro gX: 1.3125 gY: -0.2500 gZ: 2.6875

Angles X: -31.9187 Y: -3.4360 Z: 0.9829

G force: 9.8562

1

dTS (ms): 10213

ACC aX: 0.7200 aY: 5.2900 aZ: 8.4300

Gyro gX: 1.8750 gY: -3.5000 gZ: -0.5000

Angles X: -32.0240 Y: -3.8242 Z: 1.0978

G force: 9.9232